

Correction

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Correction: An improved artificial potential field method for multi-AGV path planning in ports (*Intell. Robot.* 2025; 10.20517/ir.2025.02)

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How to cite this article: Chen, X.; Chen, C.; Wu, H.; Postolache, O.; Wu, Y. Correction: An improved artificial potential field method for multi-AGV path planning in ports (*Intell. Robot.* 2025; 10.20517/ir.2025.02). *Intell. Robot.* 2025, 5(3), 661. <https://dx.doi.org/10.20517/ir.2025.33>

Received: 31 Jul 2025 **Accepted:** 31 Jul 2025 **Published:** 1 Aug 2025

Academic Editor: Simon Yang **Copy Editor:** Pei-Yun Wang **Production Editor:** Pei-Yun Wang

MAIN TEXT

Correction to *Intell. Robot.* 2025; 10.20517/ir.2025.02

The author name in the original published article^[1] is incorrectly written. More specifically, the author Yuzheng Wu^[1] should be Yuzhen Wu.

We apologize for any further confusion that may arise. The original article has been updated accordingly.

REFERENCES

1. Chen, X.; Chen, C.; Wu, H.; Postolache, O.; Wu, Y. An improved artificial potential field method for multi-AGV path planning in ports. *Intell. Robot.* 2025, 5, 19-33. DOI



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