

Addendum

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## Addendum: Liquid metal-based strain-sensing glove for human-machine interaction (*Soft Sci* 2023; 10.20517/ss.2023.26)

Pengcheng Wu<sup>1,#</sup>, Chun Ki Yiu<sup>1,2,#</sup>, Xingcan Huang<sup>1</sup>, Jiyu Li<sup>1,2</sup>, Guoqiang Xu<sup>1</sup>, Yuyu Gao<sup>1</sup>, Kuanming Yao<sup>1</sup>, Lung Chow<sup>1</sup>, Guangyao Zhao<sup>1</sup>, Yawen Yang<sup>1</sup>, Yanli Jiao<sup>1,2</sup>, Xinge Yu<sup>1,2,\*</sup>

<sup>1</sup>Department of Biomedical Engineering, City University of Hong Kong, Hong Kong 999077, Hong Kong, China.

<sup>2</sup>Hong Kong Center for Cerebro-Cardiovascular Health Engineering, Hong Kong 999077, Hong Kong, China.

<sup>#</sup>Authors contributed equally.

\*Correspondence to: Prof. Xinge Yu, Department of Biomedical Engineering, City University of Hong Kong, 83 Tat Chee Avenue, Kowloon Tong, Hong Kong 999077, Hong Kong, China. E-mail: xingeyu@cityu.edu.hk

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### MAIN TEXT

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In the original publication<sup>[1]</sup>, the Ethical approval and consent to participate was not included. According to journal requirements, the authors have now provided the necessary ethical approval and informed consent information. The following statement has been added to the online version of the article:

“This study was conducted in accordance with the ethical guidelines and principles set forth by the Internal Review Board (IRB) of the City University of Hong Kong under approval number HU-STA-00000850. All participants were informed about the experimental procedure and signed the informed consent forms prior to participation.”



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This addendum does not affect the scientific content or conclusions of the original article. We apologize for this oversight.

## REFERENCES

1. Wu, P.; Yiu, C. K.; Huang, X.; et al. Liquid metal-based strain-sensing glove for human-machine interaction. *Soft. Sci.* **2023**, *3*, 35.  
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