

Correction

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Correction: An improved artificial potential field method for multi-AGV path planning in ports (*Intell. Robot.* **2025**; 10.20517/ir.2025.02)

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MAIN TEXT

Correction to *Intell. Robot.* **2025**; 10.20517/ir.2025.02

The author name in the original published article^[1] is incorrectly written. More specifically, the author Yuzheng Wu^[1] should be Yuzhen Wu.

We apologize for any further confusion that may arise. The original article has been updated accordingly.

REFERENCES

1. Chen, X.; Chen, C.; Wu, H.; Postolache, O.; Wu, Y. An improved artificial potential field method for multi-AGV path planning in ports. *Intell. Robot.* **2025**, *5*, 19-33. DOI



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