## Nomenclature

$A_{i}$	effective cross-sectional area of rotary valve port
$A_p$	effective cross-area of piston
$B_d$	damping coefficient of motor
$B_o$	effective damping coefficient of the rack and pinion
$B_{sw}$	damping coefficient of the input shaft
$C_{q}$	flow coefficient
$C_{21}$	front wheel tire stiffness
$C_{23}$	rear wheel tire stiffness
$C_{a1}$	angular stiffness of the stabilizer bar of the front suspension
$C_{a2}$	angular stiffness of the stabilizer bar of the rear suspension
$D_{21}$	damping coefficients of the front suspension
$D_{23}$	damping coefficients of the rear suspension
$E_1$	front roll-steer coefficients
$E_2$	rear roll-steer coefficients
d	pneumatic trail
$F_{h}$	force applied by hydraulic cylinder
$F_r$	force applied by rack
$F_{ss}$	force applied by steering shaft
$I_x$	Inertia product of vehicle mass on x axes
$I_{xz}$	Inertia product of vehicle mass on x and z axes
$I_z$	Inertia product of vehicle mass on z axes
$J_{_m}$	moment of inertia of motor
$J_{sw}$	moment of inertia of the input shaft
$k_1$	stiffness coefficient of front wheel
$k_{\mathrm{p}}$	load torque coefficient of hydraulic pump
$K_{s}$	stiffness coefficient
$k_1$	stiffness coefficient of front wheel
$k_2$	stiffness coefficient of rear wheel
m	vehicle mass
$m_s$	sprung mass
$m_o$	effective mass of the rack and pinion
n	speed of motor
$n_1$	transmission ratio from the steering screw to front wheel
$p_{b}$	stator thickness of hydraulic pump
$P_{E-loss}$	energy loss of ECU
$P_{m-loss}$	energy loss of motor
$P_{MPK}$	mechanical system output power
$P_{p-loss}$	energy loss of hydraulic pump
$P_s$	output pressure of hydraulic pump
$P_{v-loss}$	energy loss of rotary valve
$Q_s$	total flow of hydraulic pump

- q displacement of hydraulic pump
- $r_n$  radius of the rack and pinion
- $R_1$  short axis radius of hydraulic pump
- $R_2$  long axis radius of hydraulic pump
- $R_a$  armature resistance of motor
- $R_{elec}$  external resistance of motor
- t vane thickness of hydraulic pump
- $T_m$  driving torque of motor
- $T_{sw}$  torque of the input shaft
- $T_r$  aligning torque
- *u* velocity of vehicle
- $U_s$  supply voltage of motor
- w gap width of rotary valve
- $x_o$  displacement of the rack and pinion
- Z vane number of hydraulic pump
- $\theta_p$  rotation angle of front wheel
- $\theta_{sw}$  rotation angle of the input shaft
- $\beta$  sideslip angle
- $\delta$  rotation angle of front wheel
- $\omega_r$  yaw rate
- $\phi$  body roll angle